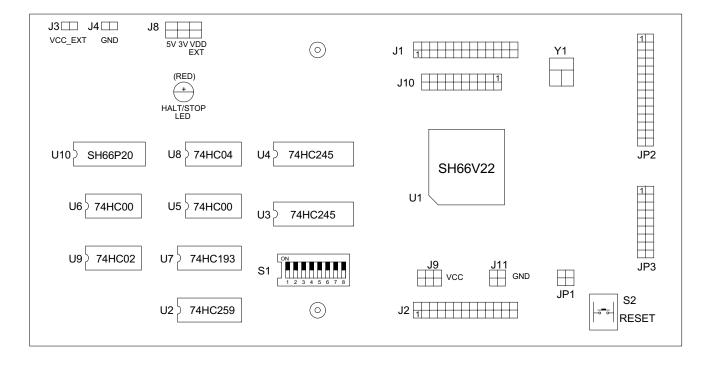


Application Notice for SH6622 EVB

SH6622 EVB

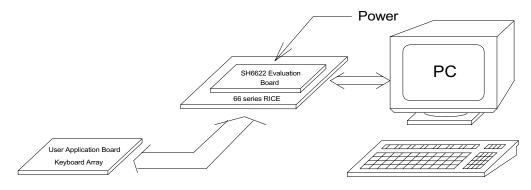
The SH6622 EVB is used to evaluate the SH6622 chip's function for the development of application program. It contains of a SH66V22 chip to evaluate the functions of SH6622. The following figure shows the placement diagram of SH6622 EVB.



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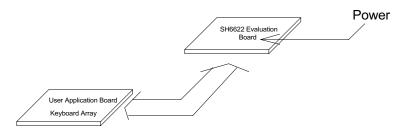


There are two configurations of SH6622 EVB in application development: ICE mode and stand-alone mode. In the ICE mode, the SH66xx ICE (motherboard) is connected to the SH6622 EVB by the ICE interface.



(a) ICE mode

In the standalone mode, the SH6622 EVB is no longer connected to the motherboard. But the EPROM board has must be connected to the SH6622 EVB by the EPROM interface. The EPROMs which may be the 27512 or 27256 store the application program;.



(b) Stand-alone mode

The process of your program's evaluation on SH6622 EVB

Uasm66.exe: assemble the program, and get binary (*.obj) file and the other files. Depart the one 16 bits obj file to the two 8 bits files by convert.exe.

Usage example (for example: aaa.asm):

- 1.Run the SH66 series assemble program:
 - C: >uasm66 aaa.asm; to produce the obj file: aaa.obj
- 2. Depart the aaa.obj to two 8 bits files aaah.obj and aaal.obj, for example:
 - C: > convert
 - Input the 16 bits (.obj) file aaa.obj

Then aaah.obj and aaal.obj will be created.

- 3. Write the aaah.obj to EPROM (ROMH)
 - Write the aaal.obj to EPROM (ROML)
- 4. Put the two EPROMs (ROML and ROMH) on the EPROM board.
- 5. Then put the EPROM board on the EVB by J9, J10 and J11.

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SH6622 EVB Programming Notices:

- Clear data RAM and initialize all system registers at the beginning.
- 2. Do not perform logical operation with I/O ports. Especially when the I/O ports have external connections.
- 3. Do not perform arithmetic operation with those registers only have 1, 2 or 3 bits. This kind of operation may not get the result you expected.
- 4. Never use reserved registers.
- 5. If "IE" instruction (interrupt enable) is set outside the interrupt processing program and there is "HALT" or "STOP" instruction, this two instructions should be followed "IE" instruction closely.
- After CPU responding to an interrupt, IRQ should be cleared before resetting IE in order to avoid many responses to one interrupt.
- 7. Interrupt Enable instruction will be automatically cleared after entering interrupt-processing program. If setting IE too early, there is a possibility of re-entry the interrupt. So the Interrupt Enable instruction should be placed at the end and followed closely by two instructions include "RTNI".
- 8. During the two successive instruction cycles next to Interrupt Enable instruction, CPU will not respond to any interrupts.
- 9. After CPU responding to interrupts, each bit of IE will be cleared by hardware while IRQ should be cleared by software.
- 10. It is necessary to add NOP before or after the HALT instruction, else the CPU will execute error instruction when it wakes up from the HALT.

NOP HALT NOP

11. It is wise to set Interrupt Enable flag before you return from subroutine in two instruction.

LDI IE, 04H; Enable timer0 interrupt LDA Temp,0

12. When you set Interrupt enable flag as the following and your subroutine do not set Interrupt Enable flag, then your system will never wake up if an interrupt entered between the NOPs.

Sample: incorrect use!

```
LDI IE, 1111B; IE = Interrupt enable flag
NOP
NOP
NOP
HALT
```

- 13. To add "p=66xx" and "romsize=xxxx" at the beginning of a program. If any problem is found in compiling the program, check if the SH6566.dev is located at the program directory.
- 14. When setting Timer Counter, first fill TOL, then TOH.
- 15. After setting TM0, TOL, TOH, it is unnecessary to reset them after interrupt each time. If TM0, TOL, TOH are reset after each TIMER interrupt, interrupt interval time will not equal because the interrupt timing is not successive.
- 16. Any instruction containing writing to or reading form memory, it should not be used to operate with I/O Port. It is best to avoid using those instructions such as "SUB, ADD " which do not contain Write operation with I/O Port but have computation operation.
- 17. "1" must be written to I/O Port before Reading.
- 18. Writing "1" to I/O Open Drain and then entering "STOP" will cause current leakage ranging from tens to hundreds micro-ampere. So pull up or pull down resistors value from 1 to 2 M Ω must be used to prevent I/O Float when I/O in Open Drain mode.
- 19. Directly reading PORT states ensure the count is correct.
- 20. Interrupt activating from STOP at the first time can save power.
- 21. When the Compiler of old version compiles program, the last line will be read twice. So, if the last line is an instruction, two same operations will be occurred. If there is Label in the last line, compiler will give an error named 'repeated definition'. This will happen in main program or included files and it is recommended that the last line should be a blank line or END.
- 22. The stack has four layers, if an interrupt is enabled, there only have three layers can be used. Otherwise, if an interrupt comes, the stack will be overflowed that will cause CPU Reset or other errors.

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- 23. Key De-bounce time is recommended to be 50ms. If a user use Rubber Key, it is best to test Rubber Key's De-bounce time.
- 24. Index register DPH and DPM both have three bits only, so pay attention to the referred address when using them.
- 25. It takes 0.3 second to wake up from STOP when using 32768Hz crystal. So, if the system is waked up by key pressing, the key may have been released when the program begins to read Key value. Please pay more attention to this problem.
- 26. The "NOP" instruction should be added at the beginning of the program to ensure the IC is stability.
- 27. SH66P20/22 Simulation Results Conflicting with OTP:
 - Program is correct when debugged on 66 series simulation board but found mistakes after writing to SH66P22/20, this may be due to the following reasons:
 - (a) Although, the clock of TIMER0 is from outer clock T0 and T0 pull high in SH66P22/20, TH0 and TL0 will automatically increase by 1 when reading the TIMER0 COUNTER. This is not equal to the simulation results.
 - (b) Although there are only DPM and DPL in SH66P22's system registers. We can't forget to assign initial value 00H to DPH (012H) during programming.
 - (c) It's recommended to assign initial value to all the SH66P22's system registers in programming when using SH66P20.
- 28. SH6622 EV board is designed for both SH6620 and SH6622.

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SH6622/P22 interface connector: JP2 (TOP View from EVB)

PORTE[2]	1	PORTE[1]
PORTE[3]		PORTE[0]
PORTF[1]		PORTF[0]
PORTA[2]		PORTA[1]
PORTA[3]		PORTA[0]
TO		
RESETB		
GND		VDD_EXT
PORTB[0]		PORTC[3]
PORTB[1]		PORTC[2]
PORTB[2]		PORTC[1]
PORTB[3]		PORTC[0]
PORTD[0]		PORTD[3]
PORTD[1]		PORTD[2]

SH6620/P20 interface connector : JP3 (Top View from EVB)

PORTA[2]	1	PORTA[1]
PORTA[3]		PORTA[0]
T0		
RESETB		EXOSC_IN
GND		VDD_EXT
PORTB[0]		PORTC[3]
PORTB[1]		PORTC[2]
PORTB[2]		PORTC[1]
PORTB[3]		PORTC[0]

External Vcc input: J3,J4 (The external power input when the EV. Board worked in stand alone mode. The voltage of Vcc_Ext must be 5V±5%)

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Jumper setting:

JP1 (SH6622 EVB ICE/Stand-alone mode select):

- If you short the "With ICE" position (only for ICE mode), the clock of SH6622 EVB is fed from the ICE.
- If you short the "Stand alone" positions (only for stand-alone mode), the system clock is selected by S1(bit 6, 7, 8) and JP4.

J8 (EVB power select):

- Short the 5V positions, the voltage (5V) of SH66V22 is internal source.
- Short the 3V positions, the voltage (3V) of SH66V22 is internal source.
- Short the EXT positions, the external power (2.2~6.0V, refer to SH6622 spec) of SH66V22 is input from VDD_EXT(JP3/10).

Switch setting:

S1:

- 1. If you turn on bit 1 (STACK ON/OFF) of this switch, then enable the stack function in ICE mode; else disable it.
- 2. If you turn on bit 2 (6622/6620) of this switch, then SH6620 is selected, else SH6622 is selected.
- 3. If you turn on bit 3 (INT_OPT) of this switch, then accept port interrupt with port I/O control. It means the condition of port interrupt is all **input** port must be pulled-high; else disable port I/O control, it means that the condition of port interrupt is that all **I/O** port must be pulled-high.
- 4. If you turn on bit 4 (RESET PULL-UP Res.) of this switch, then enable the pull-high resistor of reset pin; else disable it.
- 5. If you turn on bit 5 (WDT) of this switch, then WDT function is enabled; else disabled it.
- 6. OSC2, OSC1, OSC0:

If turn off bit 6, bit 7 and bit 8 of this switch, then you can input external clock by OSCI;

If only turn on bit 6 of this switch, then RC oscillator will be selected;

If only turn off bit 7 of this switch, then ceramic 400K~4MHz oscillator will be selected;

If only turn off bit 8 of this switch, then Xtal400K~4MHz oscillator will be selected;

If only turn off the 3 bits of this switch, then Xtal32.768KHz oscillator will be selected;

S2:

Reset the whole system when push the button.

LED declare:

HALT or STOP indicates:

LED is lighted when the system has gone into the HALT or STOP mode.

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Notice:

Evaluate your program with ICE indicate:

- 1. After enter to RICE66 and successfully download the user program, push the F5 (Reset) on PC keyboard before run your program when you evaluate your program with ICE. If there were abnormal response, the user should power off the ICE, guit RICE66 and wait for a few seconds before restart.
- 2. First time run RICE66, need to select an appropriate MCU type, clock frequency ... save the settings and restart RICE66 again.
- 3. Can't Step (F8) or Over (F9) a HALT and STOP instruction.
- 4. When you want to escape from HALT or STOP (in ICE mode), you should press the F5 key on PC keyboard twice.
- 5. The maximum current limit of the 3V power is 100mA, when the user uses internal 3V power to drive external device such as LED.
- 6. When EV. Board worked in "with ICE" mode, you can input the clock from EXOSC_IN (JP3/8) as the system clock. (refer to the RICE66 User's Guide)

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